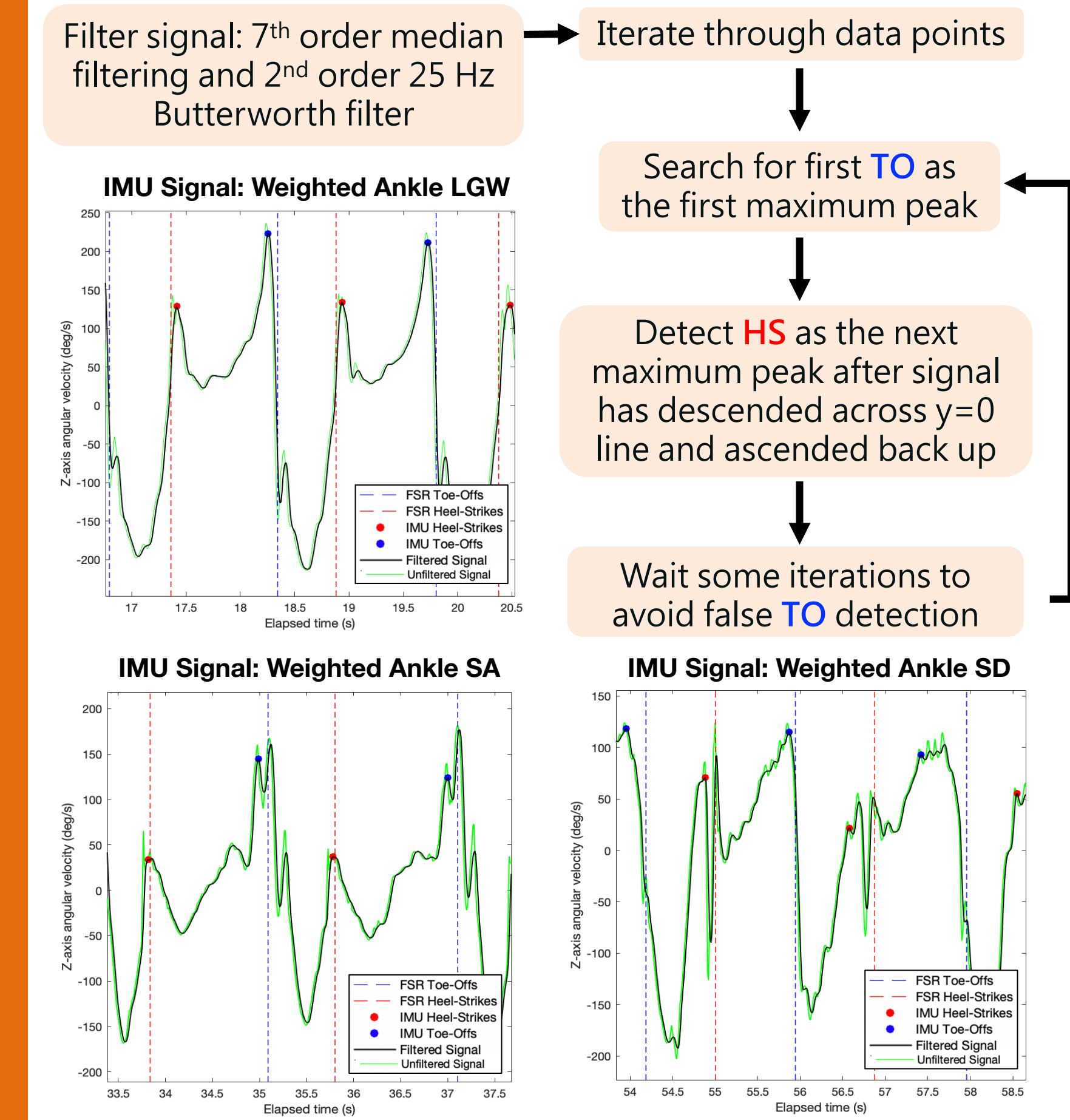


A Matlab algorithm uses the angular velocity signal to identify heel strike (HS) & toe-off (TO) events ([1,2] used for initial reference):



Algorithm conditions remained general in order to be applicable for multiple locomotion modes.

RESULTS

- Event detection timing was compared between the algorithm and the pressure sensor data.
- The accuracy of the algorithm's ability to recognize the occurrence of an event was 99%.
- The timing errors (absolute mean differences as a percentage of the average gait cycle \pm standard deviation) between the two sets of data were calculated:

	Level Ground Walking		Stair Ascent		Stair Descent	
	HS (%)	TO (%)	HS (%)	TO (%)	HS (%)	TO (%)
Unimpaired	7.87 \pm 4.13	4.71 \pm 4.15	3.24 \pm 2.76	4.84 \pm 8.39	13.63 \pm 3.39	14.56 \pm 5.75
Weighted ankle	3.57 \pm 2.73	6.38 \pm 2.53	2.49 \pm 3.45	6.14 \pm 1.31	11.50 \pm 4.10	18.15 \pm 8.07

CONCLUSION & RELEVANCE

- Although 99% of gait events were detected, future work should include refining the algorithm to improve timing error and performing a validation study of the algorithm compared to a gold-standard, especially on participants with lower-limb impairments.
- Assessment of gait patterns using a wearable system provides a wireless, multi-mode, and cost-effective solution to objectively monitor the gait rehabilitation process of children and youth with disabilities.



(Image: North News & Pictures Ltd. "Bladerunner legs transform life of boy who lost his to meningitis." 06-Oct-2014. Available: <https://www.mirror.co.uk/news/uk-news/brave-boy-who-lost-legs-4403456>.)

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Development and preliminary evaluation of a versatile gait event detection algorithm using wearable inertial sensors

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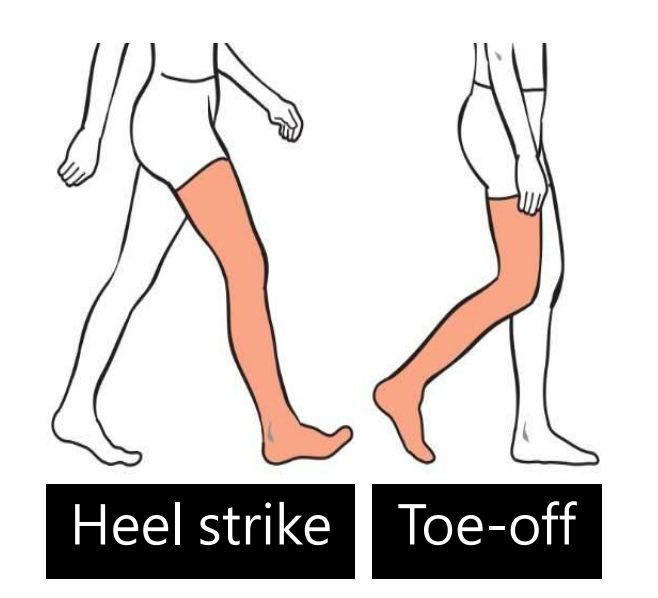


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INTRODUCTION

- Children and adults with lower-limb impairments commonly experience atypical walking (gait) patterns as they re-learn how to walk, requiring technologies to detect and/or measure these gait abnormalities.
- Inertial sensors can provide wearable and cost-effective gait analysis, compared to expensive lab technology.
- Objectively determining gait patterns can help quantify an individual's rehab progress, provide biofeedback, or even improve control of their assistive device.
- Gait parameters (e.g. stride duration) are used to assess gait patterns, which can be calculated by identifying gait events (i.e. heel strike and toe-off).



J. Tomasi, "Development and Evaluation of a Sensor System to Monitor the Stance-Phase Control Function of the Automatic Stance-Phase Lock (ASPL) Mechanism," Thesis, 2016.

Previous Research:

- single locomotion mode (level ground walking or stair ascent/descent)
- able-bodied participants [1,2]

Our Focus:

- multiple mode types
- simulate impairments

An inertial sensor system can provide an accessible solution to assess multi-mode walking patterns of individuals with lower-limb impairments.

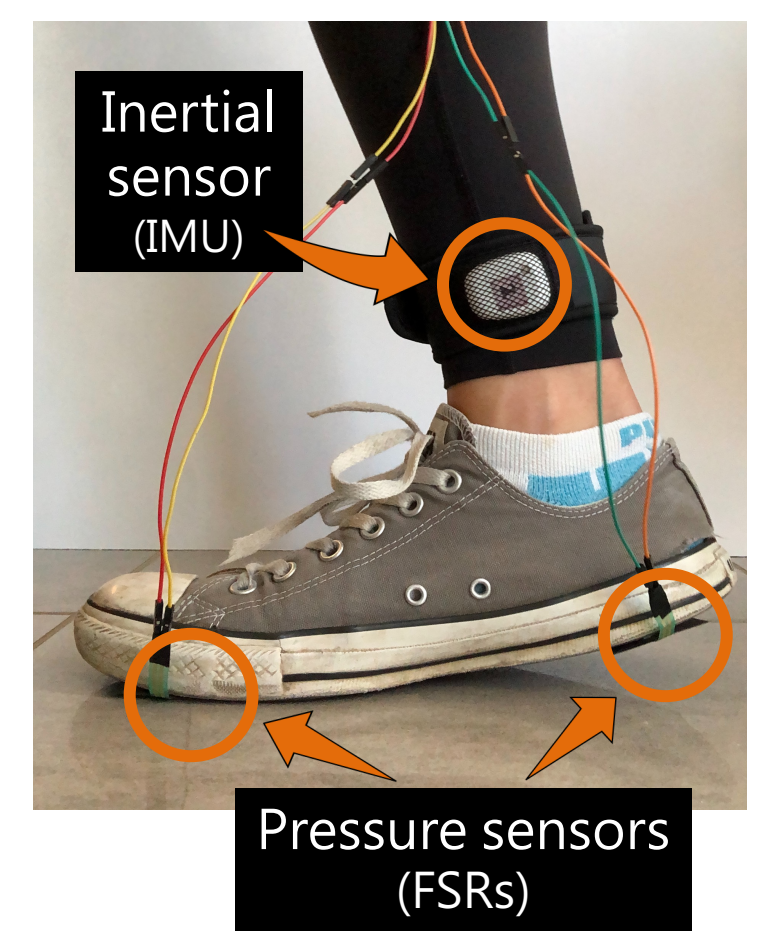


PROJECT AIM

Develop a versatile gait event detection algorithm for those with lower-limb impairments that analyses wearable inertial sensor signals

PRELIMINARY SETUP

- A preliminary assessment of algorithm performance was performed on walking trial data.
- Angular velocity signals were collected from inertial sensors.
- Pressure sensors adhered under the foot were used for validation (a common practice).
- Two walking trial samples were collected for each data type and walking mode combination:



Walking Trial Data	Walking Trial Modes
1. No alterations	1. Level ground walking (LGW)
2. Wearing ankle weight to simulate gait deviation due to lower-limb impairment [3]	2. Stair ascent (SA)
	3. Stair descent (SD)